Seat No.:	Enrolment No.

GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VII EXAMINATION - SUMMER 2016

Subject Code:172402		t Code:172402 Date:07/05/201	Date:07/05/2016	
Tir	ne:02 truction 1. 2.	Attempt all questions.	70	
Q.1	(a)	Discuss operational behavior of Induction motor with unbalanced rotor impedance. Support your answer by necessary diagrams. Describe working of Switch Polyetance Motor with post diagrams.	07 07	
Q.2	(b)(a)(b)	Describe working of Switch Reluctance Motor with neat diagrams. Write a technical note on: Vector control of synchronous motor. Explain the basic principle of sensor less control of Induction Motor Drives. OR	07 07 07	
	(b)	Discuss basic principle of DTFC with necessary diagrams.	07	
Q.3	(a)	"Stator voltage control method is not suitable for constant load torque drive",	07	
	(b)	justify the statement. Discuss advantages of Power Electronics based speed control methods over traditional methods for induction motor.	07	
Q.3	(a) (b)	OR Enlist various methods for speed control of Induction motor. Explain V/f control of IM with necessary equations. Explain speed control of IM using power electronics converter for Rotor		
Q.4	(a) (b)	Resistance method. Discuss basic principle of vector control with necessary diagrams. Derive equation for slip power. Also explain traditional method for slip power recovery.	07 07	
ΩA	(a)	OR Describe implementation of indirect flux oriented yeater central method for IM	07	
Q.4	(a) (b)	Describe implementation of indirect flux oriented vector control method for IM. Write a short note on: Static Kramer drive for slip power recovery.	07	
Q.5	(a) (b)	Explain dynamic modeling of Induction Motor with necessary equations. Enlist speed control methods for synchronous motor. Discuss adjustable frequency operation in brief.	07 07	
Q.5	(a) (b)	OR Discuss reference frame theory for induction motor in brief. Draw & explain self controlled synchronous motor drive using load commutated thyristor based inverter.	07 07	
