

GUJARAT TECHNOLOGICAL UNIVERSITY
BE - SEMESTER-VII EXAMINATION – WINTER 2015

Subject Code: 171003**Date: 09/12/2015****Subject Name: Digital Signal Processing****Time: 10:30am to 1:00pm****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

- Q.1** (a) With the block diagram explain typical Digital Signal Processing system and also mention the advantages of DSP over ASP. **07**
- (b) For each of the following systems, determine whether the system is Static /dynamic, Causal/ Noncausal, Linear/ Nonlinear, Time invariant / Time variant **07**
- (i) $y[n] = x[n] + 3u[n+1]$
- (ii) $y[n] = x[a n]$ where 'a' is any integer greater than 1.
- Q.2** (a) Define Discrete Fourier series, Discrete time Fourier transform and Discrete Fourier transform and explain the relation between them. **07**
- (b) i. The impulse response of the LTI system is $h(n) = \{2, 4, 5, 6\}$. **07**
- ↑
- Determine the response of the system to the input signal $x(n) = \{1, 1, 2, 3\}$
- ↑
- ii. Find the auto correlation of the discrete sequence $x(n) = a^n u(n)$ for $0 < a < 1$
- OR**
- (b) What is ROC? Explain the properties of the ROC in Z-Transform. **07**
- Q.3** (a) Find the z transform of $x(n) = n^2 e^{-2n} u(n)$ using the necessary properties. **07**
- (b) Find the solution for the given the difference equation $y(n) + b^2 y(n-2) = 0$ for $n \geq 0$ where $|b| < 1$ and initial conditions are $y(-1) = 0$, $y(-2) = -1$ **07**
- OR**
- Q.3** (a) Draw the structures of the following discrete time system defined by the difference equation $y(n) - \frac{3}{4} y(n-1) + \frac{1}{8} y(n-2) = x(n) + \frac{1}{3} x(n-1)$ **07**
- (i) Direct Form-I
- (ii) Direct Form-II
- (iii) Cascade Form
- (b) Explain Inverse system, minimum phase system and all pass system. Determine Inverse of the system characterized by $y(n) = 0.5y(n-1) + x(n)$ assuming zero initial conditions. **07**
- Q.4** (a) Explain Impulse invariant method for IIR Filter design. **07**
- Determine $H(z)$ by using Impulse invariant method if $H(s) = \frac{10}{s+2}$ and sampling time is 0.01sec
- (b) Determine the Circular convolution of the two sequences $x_1(n) = \{2, 7, 5, 8, 9\}$ and $x_2(n) = \{1, 3, 2, 4, 5\}$ **07**

OR

- Q.4** (a) Using DFT and IDFT method compute linear convolution of two sequences **07**
 $x_1(n)=\{2,3,5\}$ and $x_2(n)=\{1,3\}$
(b) Explain the window functions used in FIR filter design. **07**

- Q.5** (a) A digital low pass Butterworth filter with a 3db bandwidth of 0.2π is to be **07**
designed from analog filter whose system response is $H(s) = \frac{\Omega_c}{s + \Omega_c}$.
Use bilinear transformation & obtain $H(z)$.

- (b) State and prove any four properties of DFT **07**

OR

- Q.5** (a) Derive the 8 point Radix 2 DITFFT algorithm to compute DFT. Also explain the **07**
bit reversal concept in it.
(b) Explain multiplier-Accumulator (MAC) hardware in DSP processors **07**
