GUJARAT TECHNOLOGICAL UNIVERSITY ME - SEMESTER–I(New course)• EXAMINATION – WINTER- 2015

Subject Code: 2710313 Date: 04/01/2 Subject Name: Advance Industrial Drives & Control				
Time:2:30 pm to 5:00 pm Total Marks: Instructions:				
		Attempt all questions. Make suitable assumptions wherever necessary. Figures to the right indicate full marks.		
Q.1	(a)	Classify types of BLDC Motor. Discuss construction & working of BLDC Motor.	07	
	(b)	Draw only the construction of permanent magnet stepper motor. Describe operation of unipolar drive circuit for variable reluctance stepper motor with necessary diagrams.	07	
Q.2	(a) (b)	Enlist & explain various factors affecting for selection of AC motor drive. Discuss dynamic modelling of Induction motor with necessary diagrams & Equations.	07 07	
		OR		
	(b)	Write a short note on Dynamic Model of separately excited DC Motor.	07	
Q.3	(a)	Draw speed-torque characteristics for DC shunt, DC series & PMDC motor. Derive equation for speed for series DC motor.	07	
	(b)	Discuss Self-controlled synchronous motor drive employing load commutated inverter with neat circuit diagram.	07	
		OR	~	
Q.3	(a)	Classify various speed control methods of DC motor. Describe it with necessary equations.	07	
	(b)	Describe Cycloconverter fed synchronous motor drive with neat circuit diagram.	07	
Q.4	(a)	Discuss Vector control of synchronous motor with necessary diagrams & equations.	07	
	(b)	Discuss Direct Torque Control (DTC) method for speed control of Induction Motor.	07	
		OR		
Q.4	(a)	Describe various control strategy for control of Synchronous Reluctance Motor.	07	
	(b)	Explain principle of indirect vector control for IM with necessary diagrams.	07	
Q.5	(a)	"Stator voltage control method is not suitable for constant load torque drive", Justify the statement.	07	
	(b)	Enlist various advantages of multilevel converters used for induction motor drive in brief.	07	
		OR		
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Q.5(a) Discuss the concept of sensor less vector control for induction motor.07(b) Write a short note on Model Reference Adaptive System.07
